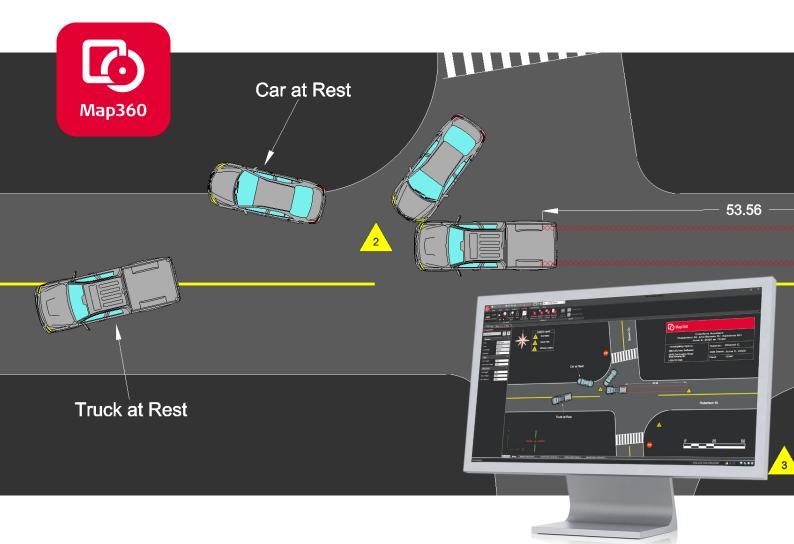
## **Leica Map360** Digitise. Analyse. Present.





### Digitise

A common problem many agencies face is how to make efficient use of all the data captured at a scene. Map360 can transform the data from a wide range of mapping devices into useful information that preserves the evidence from the scene.



#### Analyse

Easy to use tools enhance the quality of incident reconstructions and provide critical details from the measured evidence. We provide a suite of analysis tools to verify the data accuracy and help calculate speed, momentum, crush and much more. Quickly analyse bullet trajectories and bloodstain impact patterns and explore witness viewpoints.



#### Present

Visually communicate the critical details of a scene with diagrams, pre-incident plans, and other courtroom exhibits that are easy to understand. Various reports can be easily created and shared complete with photos, videos and evidential documents included.



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- when it has to be **right** 



# Leica Map360 Desktop Software

| GENERAL                                 |
|---|
| Ease of Use                             |
| Fluid 2D/3D Navigation                  |
| Universal File: DWG/DXF                 |
| Engineering grade CAD engine            |
| Geodetic support and tools              |
| LICENSING                               |
| CLM Licensing                           |
| Local and Network                       |
| DIAGRAMS                                |
| Drawing & Editing Tools                 |
| Dimensioning & Labeling                 |
| Layer Control                           |
| Evidence Markers                        |
| Symbol & Model Library - 2D, 3D         |
| Vehicles Specs Database                 |
| Layout and Viewport Control (Templates) |
| Body poser 2D/3D                        |
| Room / Building outlines                |
| Advanced Lines                          |
| 2D Plan Views                           |
| 3D Views                                |

#### IMPORT

| Baseline Offset / Triangulation - MANUAL INPUT        |
|---|
| Points (ACII) - TXT, CSV                              |
| Evidence Recorder - Project, RAW                      |
| Captivate Jobs - DBX                                  |
| Other Observation Data - GSI, RW5, DAT, GRE, TRA      |
| Georeferenced Images - JPG, PNG, TIFF                 |
| Images - JPG, PNG, BMP, TIFF, and others              |
| OrthoSlice - DXF + PNG                                |
| Point Cloud - LGSx, E57, LAS, PTX, PTS, RCS, RCP, COE |
| HeXML/LandXML - XML                                   |
| CAD data - DWG, DXF, DGN                              |
| Models - OBJ, DAE                                     |
| BIM - IFC, IFA, RCT                                   |
| Stream - Bing Maps, Reality Cloud Studio, WMS         |
| EXPORTS   |
| Drawing - DWG, DXF                                    |
| Points (ASCII) - TXT                                  |
| PDF   |
|   |

Google Earth - KML

#### ANALYS

| ANALYSIS                            |
|-------------------------------------|
| Time & Distance                     |
| Reconstruction Calculations         |
| Momentum Angles                     |
| Crush Analysis                      |
| Bullet Trajectory Analysis          |
| Bloodstain Pattern Analysis         |
| Witness View/Camera                 |
| POINT CLOUD                         |
| Render Speed                        |
| Visualization Tools                 |
| TruSpace                            |
| DELIVERABLES / REPORTS              |
| Diagrams                            |
| PDF export with layer support       |
| Snippets / Witness Views            |
| Evidence Reports                    |
| Scanner QA Report                   |
| Crush Report                        |
| Trajectory Analysis Reports         |
| Bloodstain Pattern Analysis Reports |
| Point Cloud and Model Viewer        |
|                                     |

|                              | Map360 Sketch  | Map360 Standard  | Map360 Pro                              |  |
|------------------------------|--|--|---|--|
| FEATURES                     |  |  |   |  |
| 2D Viewing and Navigation    | ~  | <b>v</b>   | V                                       |  |
| 2D Diagrams                  | ~  | <b>v</b>   | <i>v</i>                                |  |
| Symbol Library               | ~  | <b>v</b>   | <i>v</i>                                |  |
| Evidence Markers and Reports | V  | <ul> <li></li> </ul>   | <ul> <li></li> </ul>                    |  |
| Supports Manual measurements | V  | <ul> <li></li> </ul>   | ~                                       |  |
| Stream Bing Maps             | <i>v</i>   | <ul> <li>✓</li> </ul>  | <i>v</i>                                |  |
| Import Point Data            | V  | <ul> <li></li> </ul>   | <b>~</b>                                |  |
| Import Imagery               | V  | <ul> <li></li> </ul>   | <ul> <li></li> </ul>                    |  |
| Import OrthoSlice            | V  | <ul> <li>✓</li> </ul>  | V                                       |  |
| Analysis Tools               |  | <ul> <li></li> </ul>   | <i>v</i>                                |  |
| 3D Viewing and Navigation    |  | <ul> <li>✓</li> </ul>  | V                                       |  |
| 3D Diagrams                  |  | <ul> <li></li> </ul>   | V                                       |  |
| Import Evidence Recorder     |  | <ul> <li>✓</li> </ul>  | V                                       |  |
| Import Captivate             |  | <ul> <li>✓</li> </ul>  | <b>v</b>                                |  |
| Import Point Cloud           |  |  | V                                       |  |
| Point Cloud Tools            |  |  | V                                       |  |
| RECOMMENDED REQUIREMENTS     |  |  |   |  |
| Processor                    | Intel® Core™ i5 or comparable  | Intel® Core™ i5 or comparable  | Intel® Core™ i7 or comparable           |  |
| RAM                          | 8 to 16GB  | 8 to 16GB  | 16 to 64GB                              |  |
| Hard Drive                   | Map360 install package is approximately 5GB                                | Map360 install package is approximately 5GB                                | Internal SSD drives, 500GB or<br>higher |  |
| Graphics                     | Support for OpenGL 1.4 or higher<br>1024 x 768 VGA or higher<br>resolution | Support for OpenGL 1.4 or higher<br>1024 x 768 VGA or higher<br>resolution | NVIDIA GTX 10 series or comparable      |  |
| Notes                        | Dedicated graphics device with dedicated memory is recommended.            |  |   |  |